ICSE Board Syllabus for Class 12 Math

COURSE STRUCTURE MATHEMATIC

CLASS 12

SECTION A

Determinants and Matrices

(i) Determinants

- Order.
- Minors.
- Cofactors.
- Expansion.
- Properties of determinants.
- Product of determinants (without proof).
- Simple problems using properties of determinants e.g. evaluate b
- Cramer's Rule
- . Solving simultaneous equations in 2 or 3 variables,
- . Consistency, inconsistency.
- . Dependent or independent.

NOTE: the consistency condition for three equations in two variables is required to be covered.

(ii) Matrices Types of matrices (m x n; m, $n \le 3$), order; Identity matrix, Diagonal matrix.

- Symmetric, Skew symmetric.
- Operation addition, subtraction, multiplication of a matrix with scalar, multiplication of two matrices (the compatibility).
- Singular and non-singular matrices.

•Existence of two non-zero matrices whose product is a zero matrix.

- Martin's Rule (i.e. using matrices)
- a 1x + b 1y + c 1z = d 1.AdjA/A a 2x + b 2y + c 2z = d 2.

a 3x + b 3y + c 3z = d 3.

AX = B X = A - 1 B

NOTE: The conditions for consistency of equations in two and three variables, using matrices, are to be covered

2 Boolean Algebra

Boolean algebra as an algebraic structure, principle of duality, Boolean function. Switching circuits, application of Boolean algebra to switching circuits.

3 Conics

- As a section of a cone.
- Definition of Foci, Directrix, Latus Rectum.
- . Simple problems based on above.
- PS = ePL where P is a point on the conics, S is the focus, PL is the perpendicular distance of the point from the directrix.

(i) Parabola

•e =1, y2 = 4ax, x2 = 4ay, y2 = -4ax,
x2 = -4ay, (y -
$$\beta$$
)2 = 4a (x - α),
(x - α)2 = 4a (y - β).

•Rough sketch of the above.

•The latus rectum; quadrants they lie in; coordinates of focus and vertex; and equations of directrix and the axis.

•Finding equation of Parabola when Foci and directrix are given.

•Simple and direct questions based on the above.

(ii) Ellipse

•Cases when a > b and a < b.

•Rough sketch of the above.

•Major axis, minor axis; latus rectum; coordinates of vertices, focus and centre; and equations of directrices and the axes.

•Finding equation of ellipse when focus and directrix are given.

•Simple and direct questions based on the above.

•Focal property i.e. SP + SP' = 2a.

(iii) Hyperbola

x2 y 2 - = 1, e > 1, b 2 = a 2 (e 2 - 1) a 2 b 2

• Cases when coefficient y2 is negative and coefficient of x2 is negative.

- Rough sketch of the above.
- Focal property i.e. SP S'P = 2a.
- Transverse and Conjugate axes; Latus rectum; coordinates of vertices, foci and centre; and equations of the directrices and the axes.

x2 y2+ 2 = 1 , e <1, b2 = a 2 (1 - e2)2a b

- General second degree equation ax 2 + 2hxy + by 2 + 2 gx + 2 fy + c = 0 represents a parabola if h2 = ab, ellipse if h2 < ab, and hyperbola if h2 >ab. Condition that y = mx + c is a tangent to the conics.
- . Inverse Trigonometric Function
- Principal values.
- sin-1x, cos-1x, tan-1x etc. and their graphs.
 sin-1x = cos −1 1 − x 2 = tan −1

. Addition formulae.

 $(\cos x \pm \cos y = \cos (xy \operatorname{msin-1} x \pm \sin - 1y = \sin - 1x 1 - y2 \pm y 1 - x2 - 1)$ similarly $\tan - 1x \pm \tan - 1y = \tan - 1$

- . Similarly, establish formulae for 2sin-1x, 2cos-1x, 2tan-1x, 3tan-1x etc. using the above formula.
- Application of these formulae.
- 5 Calculus
- (i) Differential Calculus
- •Revision of topics done in Class XI mainly the differentiation of product of two functions, quotient rule, etc.
- Derivatives of trigonometric functions.
- Derivatives of exponential functions.
- Derivatives of logarithmic functions.
- Derivatives of inverse trigonometric functions - differentiation by means of substitution.
- Derivatives of implicit functions and chain rule for composite functions.
- Differentiation of a function with respect to another function e.g. differentiation of sinx3 with respect to x3.
- . Logarithmic Differentiation Finding
- dy/dx when y = x
- •Successive 2nd order.
- L'Hospital's theorem.

Rolle's Mean Value Theorem - its geometrical interpretation.

- •Lagrange's Mean Value Theorem its geometrical interpretation.
- Maxima and minima.
- (ii) Integral Calculus
- Revision of formulae from Class XI.
- Integration of 1/x, ex, tanx, cotx, secx, cosecx.
- Integration by parts.
- Integration by means of substitution.
- Properties of definite integrals.

Problems based on the following properties of definite integrals are to be covered.

- Application of definite integrals area bounded by curves, lines and coordinate axes is required to be covered.
- 6 Correlation and Regression
- Definition and meaning of correlation and regression coefficient.
- Coefficient of Correlation by Karl Pearson.
- Rank correlation by Spearman's (Correction included).
- Lines of regression of x on y and y on x.

NOTE: Scatter diagrams and the following topics on regression are required.

- i) The method of least squares.
- ii) Lines of best fit.
- iii) Regression coefficient of x on y and y on x.

iv) b xy × b yx = r 2, $0 \le b$ xy × b yx ≤ 1

v) Identification of regression equations

7. Probability

- Random experiments and their outcomes.
- Events: sure events, impossible events, mutually exclusive events, independent events and dependent events.
- Definition of probability of an event.
- Laws of probability: addition and multiplication laws, conditional probability (excluding Baye's theorem).
- 8 Complex umbers
- Argument and conjugate of complex numbers.
- Sum, difference, product and quotient of two complex numbers additive and multiplicative
- Simple locus question on complex number; proving and using -
- Triangle inequality.
- Square root of a complex number.
- Demoivre's applications.
- Cube roots of unity: 1, ω , ω 2 ; application problems.
- 9 Differential Equations
- Differential equations, order and degree.
- Solution of differential equations.
- Variable separable.
- Homogeneous equations and equations reducible to homogeneous form.

- Linear form functions of x only. Similarly for dx/dy.
- NOTE: Equations reducible to variable separable type are included. The second order differential equations are excluded.

SECTIO B

- 10. Vectors
- Scalar (dot) product of vectors.
- Cross product its properties area of a triangle, collinear vectors.
- Scalar triple product volume of a parallelopiped, co-planarity.

Proof of Formulae (Using Vectors)

- Sine rule.
- Cosine rule
- Projection formula
- Area of a Δ = ½absinC

NOTE: Simple geometric applications of the above are required to be covered.

- 11. Co-ordinate geometry in 3-Dimensions
- (i) Lines

NOTE: Symmetric and non-symmetric forms of lines are required to be covered.

(ii) Planes

• Cartesian and vector equation of a plane.

• Direction ratios of the normal to the plane.

- One point form.
- Normal form.
- Intercept form.

- Distance of a point from a plane.
- Angle between two planes, a line and a plane.
- Equation of a plane through the intersection of two planes i.e. P1 + kP2 = 0.
 Simple questions based on the above

Simple questions based on the above.

12 Probability

Baye's theorem; theoretical probability distribution, probability distribution function; binomial distribution – its mean and variance.

12. Cartesian and vector equations of a line through one and two points.

Coplanar and skew lines.

Conditions for intersection of two lines.

Shortest distance between two lines.

NOTE: Theoretical probability distribution is to be limited to binomial distribution only.

SECTION C

13 Discount

True discount; banker's discount; discounted value; present value; cash discount, bill of exchange.

NOTE: Banker's gain is required to be covered.

14. Annuities

Meaning, formulae for present value and amount; deferred annuity, applied problems on loans, sinking funds, scholarships.

NOTE: Annuity due is required to be covered.

15. Linear Programming

Introduction, definition of related terminology such as constraints, objective function, optimization, isoprofit, isocost lines; advantages of linear programming; limitations of linear programming; application areas of linear programming; different types of linear programming (L.P.), problems, mathematical formulation of L.P problems, graphical method of solution for problems in two variables, feasible and infeasible regions, feasible and infeasible solutions, optimum feasible solution.

- Application of derivatives in Commerce and Economics in the following Cost function, average cost, marginal cost, revenue function and break even point.
- 17. Index numbers and moving averages
- Price index or price relative.
- Simple aggregate method.
- Weighted aggregate method.
- Simple average of price relatives.
- Weighted average of price relatives (cost of living index, consumer price index).
- NOTE: Under moving averages the following are required to be covered:
- Meaning and purpose of the moving averages.
- Calculation of moving averages with the given periodicity and plotting them on a graph.
- If the period is even, then the centered moving average is to be found out and plotted.